L Number	Hits	Search Text	DB	Time stamp
1	322186	robot and (cd medium diskette zip tape) and operational arc	USPAT;	2001/09/10 13:06
			US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT,	
			IBM TDB	
2	795861	software program instruction command and two adj state	USPAT;	2001/09/10 13:09
	775001	Software program instruction command and two day state	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
	22565	( 1 , 1 / 1 / 1 / 1 / 1 / 1 / 1 / 1 / 1 /		2001/09/10 13:09
3	22567	(robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:09
		(software program instruction command and two adj state)	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
4	448283	weighting coefficient	USPAT;	2001/09/10 13:10
			US-PGPUB;	
			ЕРО; ЛРО;	
		4	DERWENT;	
			IBM TDB	
_	3807	((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:11
5	3607	(software program instruction command and two adj state)) and	US-PGPUB;	2001/05/10 15:11
		(weighting coefficient)	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
7	3	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:12
		(software program instruction command and two adj state)) and	US-PGPUB;	
		(weighting coefficient)) and (predetermin\$3 adj probability)	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
6	467	predetermin\$3 adj probability	USPAT;	2001/09/10 13:41
	107	prodotonimos daj productivy	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM TDB	
_	271200	((C. 1. (		2001/09/10 13:43
8	371300	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13.43
		(software program instruction command and two adj state)) and	US-PGPUB;	
		(weighting coefficient)) and state model	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
9	52	(((robot and (cd medium diskette zip tape) and operational arc) and	USPAT;	2001/09/10 13:43
		(software program instruction command and two adj state)) and	US-PGPUB;	
		(weighting coefficient)) and state adj model	EPO; JPO;	
		( · · · · · · · · · · · · · · · · · · ·	DERWENT;	
			IBM TDB	
10	0	robot and medium same program and predetermin\$3 adj operartion and	USPAT;	2001/09/10 13:59
10	U		US-PGPUB;	2001/07/10 15:57
		two adj state	ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	2001/00/10 14 00
11	0	robot and medium same program and predetermin\$3 adj operartion	USPAT;	2001/09/10 14:00
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
12	0	robot and medium and predetermin\$3 adj operartion	USPAT;	2001/09/10 14:00
		1000t and medium and predeterminas and operation	US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	1

13	0	robot and medium adj10 operartion	USPAT;	2001/09/10 14:01
1		•	US-PGPUB;	
			ЕРО; ЈРО;	
			DERWENT;	
			IBM TDB	
14	4749	robot and medium	USPAT;	2001/09/10 14:01
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
	ļ		IBM TDB	
15	8	autonomous and medium and weighting adj coefficient	USPAT;	2001/09/10 14:02
			US-PGPUB;	
			ЕРО; ЛРО;	
			DERWENT;	
			IBM TDB	
16	18	(status adj transition adj chart) or (operational adj state adj model) and	USPAT;	2001/09/10 14:22
		autonomous	US-PGPUB;	
			EPO; JPO;	
			DERWENT;	
			IBM TDB	

#### 4 An agent belief system for multi-agent systems

Wenjie Wang; Zhongzhi Shi; Qijia Tian; Tao Wang Systems, Man and Cybernetics, 1996., IEEE International Conference on , Vo 1996

Page(s): 2065 -2069 vol.3

#### [Abstract] [PDF Full-Text (588 KB)] CNF

# 5 Linear topological conjugacy of elementary canonical state models three-dimensional auton mous piecewise-linear dynamical systems

Pospisil, J.; Brzobohaty, J.

Electronics, Circuits, and Systems, 1996. ICECS '96., Proceedings of the Third International Conference on , Volume: 1 , 1996

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## 6 Elementary canonical state models of Chua's circuit family

Pospisil, J.; Brzobohaty, J.

Circuits and Systems I: Fundamental Theory and Applications, IEEE Transact

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### [Abstract] [PDF Full-Text (344 KB)] JNL

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